



Three-Phase Brushless Motor Driver IC

Overview

The LB1854M is a three-phase brushless motor driver IC and is optimal, in particular, for driving VCR capstan and drum motors.

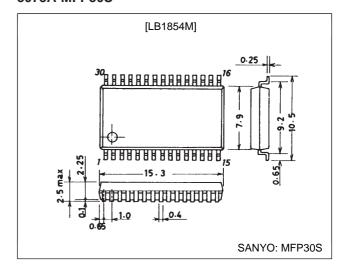
Features

- 120° voltage linear drive technique
- The LB1854M soft switching scheme allows smaller external capacitors to be used (e.g., chip capacitors).
- Built-in thermal-shutdown function
- Built-in overcurrent protection circuit
- Built-in FG amplifiers (operational amplifier and Schmitt amplifier)
- Control start voltage set by an external voltage
- The output current feedback level can be changed by changing the control gain to one of two levels.

Package Dimensions

unit: mm

3073A-MFP30S



Specifications

Absolute Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum augulu valtaga	V _{CC} 1 max		20	V
Maximum supply voltage	V _{CC} 2 max		7.0	V
Applied output voltage	V _{OU, V, W}		22	V
Maximum output current	I _{OUT} max		1.5	А
Allowable power dissipation	Pd max		1.05	W
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

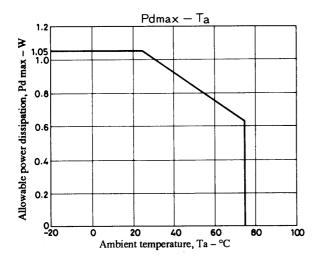
Allowable Operating Ranges at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _{CC} 1		5 to 18	V
Supply voltage	V _{CC} 2		4.3 to 6.5	V

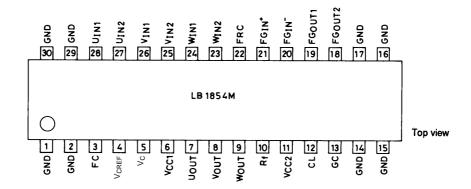
Electrical Characteristics at $Ta=25^{\circ}C,\,V_{CC}1$ = 12 $V,\,V_{CC}2$ = 5 V

Parameter	Symbol	Conditions	min	typ	max	Unit
Current drain	I _{CC} 1	$V_C = 0 \text{ V}, R_L = \infty$		17	30	mA
Current drain	I _{CC} 2	V _C = 0 V		6.5	9.5	mA
[Drive Block]						
Output saturation voltage	V _O (sat) 1	I _{OUT} = 0.5 A, sink + source		1.6	2.2	٧
Output saturation voltage	V _O (sat) 2	I _{OUT} = 1.0 A, sink + source		2.0	3.0	V
Output TRS breakdown voltage	V _O (sus)	I _{OUT} = 20 mA*	20			V
Output resting potential	V _{OQ}	V _C = 0 V	5.7	6.0	6.3	V
Hall amplifier input offset voltage	V _H offset		-5		+5	mV
Hall amplifier input bias current	I _H bias			1	5	μΑ
Hall amplifier common mode input voltage range	V _H ch		1.3		2.2	٧
Hall input/output voltage gain	GV _{HO}		43	46	49	dB
[Control Block]					•	
Control output drive gain	GV _{CO} 1	High gain	37	40	43	dB
Control output drive gain	GV _{CO} 2	Low gain	31	34	37	dB
Control output CH difference	ΔGV _{CO}		-2		+2	dB
Control start voltage	V _{CTH}	When V _{OUT} p-p = 2 V		2.5		V
Gain control switching high level			4		5	V
Gain control switching middle level		Middle level when the input is open	2		3	V
Gain control switching low level			0		1	V
[FG Amplifier]						
FG amplifier input offset voltage	V _{FG} offset		-8		+8	mV
Open-loop voltage gain	GV _{FG}	f = 1 kHz		60		dB
Source output saturation voltage	V _{FG OU}	I _O = 2 mA	37			V
Sink output saturation voltage	V _{FG OD}	$I_O = -2 \text{ mA}$			1.3	V
Common-mode signal rejection ratio	CHR	*		80		dB
FG amplifier common-mode input voltage range	V _{FG CH}		0		3.5	V
Phase margin		*		20		Deg
0.1.391	∆Vsh1	FG _{OUT} 2: High to low		22		mV
Schmitt hysteresis	∆Vsh2	FG _{OUT} 2: Low to high		22		mV
Schmitt input voltage range	Vsh _{CH}		0.7		3.5	V
[Thermal Shutdown]			•			
Operating temperature	TSD	*	150	180	210	°C
Hysteresis	ΔTSD	*		15		°C

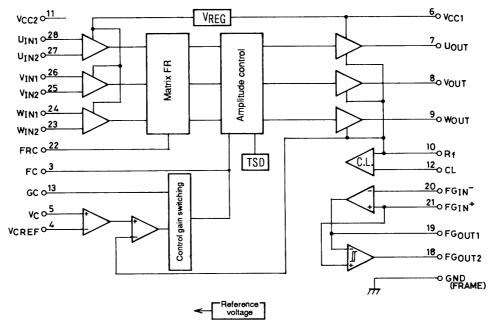
Note: * Items marked with an asterisk are design target values and are not measured.



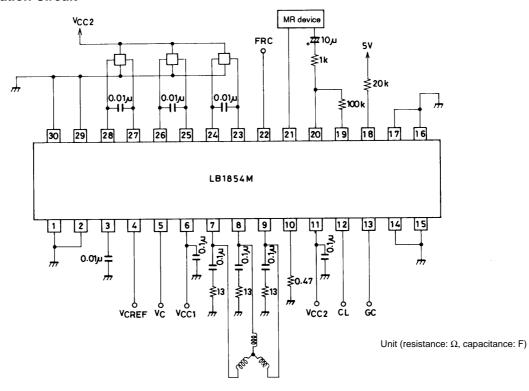
Pin Assignment



Block Diagram



Sample Application Circuit



Truth Table

	Source	Input			Forward and reverse control
	Sink	U	V	W	F/RC
4	W phase \rightarrow V phase	Н	Н		L
'	$V \text{ phase} \rightarrow W \text{ phase}$			-	Н
2	W phase \rightarrow U phase	Н			L
2	U phase → W phase		L	-	Н
3	$V \text{ phase} \to W \text{ phase}$			Н	L
3	W phase \rightarrow V phase	-		П	Н
4	$\mbox{U phase} \rightarrow \mbox{V phase}$		Н		L
4	$V \text{ phase} \to U \text{ phase}$	_	11		Н
5	$V \text{ phase} \to U \text{ phase}$	Н		Н	L
э	$\mbox{U phase} \rightarrow \mbox{V phase}$	1	L	11	Н
6	$U\;phase\toW\;phase$		Н	Н	L
	W phase \rightarrow U phase	_			Н

Input high: Phase 1 is 0.2 V or more higher than the corresponding phase 2 for each phase input. Low: Phase 1 is 0.2 V or more lower than the corresponding phase 2 for each phase input. Forward and reverse control high: 2.3 V to V_{CC}1 Low: 0 V to 0.7 V

Pin Functions

Unit (resistance: Ω)

Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
1, 2, 14, 15, 16, 17, 29, 30	FRAME (GND)			Ground for all circuits except the outputs
3	FC		VCC2 3 3.9k ♣	The gain frequency characteristics can be lowered by connecting a capacitor between this pin and ground to prevent oscillation.
4 5	V _C ref	1.5 V min V _{CC} 2 max 0 V min V _{CC} 2 max	VCC2 200µ 200µ 50µ 200 200 200 200 200 200 200 200 200 2	Speed control The LB1854M implements a voltage control scheme in which the output voltage is controlled by the pin 5 voltage. The pin 4 voltage determines the control start voltage.
6	V _{CC} 1	5 to 18 V		Power supply that provides the drive outputs

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Unit (resistance: Ω)

			T	Unit (resistance: Ω)
Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
7 8 9	U _{OUT} Vouт Wouт		VCC1 W 9 OR1	Output pins
10	R _f			Output transistor ground Feedback can be applied to the control amplifier by inserting resistor between this pin and GND and detecting the output current as a voltage. The overcurrent protection circuit (current limiter) operates by detecting the voltage on this pin.
11	V _{CC} 2	4.3 to 6.5 V		Power supply provided to all blocks other than the output block This voltage must be stabilized so that no ripple or other noise is present.
12	CL	0 V min V _{CC} 2 max	VCC2	The current limiter operates when the R _f pin reaches the same potential as pin 12. The pin 12 potential is set up externally.
13	GC	0 V min V _{CC} 2 max	VCC2 50k ₹ 10k 50k ₹	Control input to output gain switching pin High level (4 to 5 V): 34 dB Middle level (2 to 3 V) or open: 40 dB (low speed): 34 dB (high speed) Low level (0 to 1 V): 40 dB However, note that this applies when V _{CC} 2 is 5 V.
18	FG _{OUT} 2		VCC2 18	FG Schmitt amplifier output
19	FG _{OUT} 1		VCC2 38 ₹ 38 ₹ 19	FG amplifier output

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Unit (resistance: Ω)

Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
20 21	FG _{IN} - FG _{IN} +	0 V min 3.5 V max (when V _{CC} 2 is 5 V)	VCC2 (2) (3) (4) (4) (4) (4) (4) (4) (4) (4) (4) (4	FG signal input
22	FRC	High: 2.3 V min Low: 0.7 V max	VREG 30k	Motor forward/reverse control pin Low level (0.7 V or lower): forward High level (2.3 V or higher): reverse
23 24 25 26 27 28	W _{IN} 2 W _{IN} 1 V _{IN} 2 V _{IN} 1 U _{IN} 2 U _{IN} 1	1.4 V min 2.0 V max	VREG VCC2 VCC2 VCC2 VCC2 VCC2 VCC2 VCC2 VCC	W phase Hall sensor input Logic high is the $W_{IN}1 > W_{IN}2$ state. V phase Hall sensor input Logic high is the $V_{IN}1 > V_{IN}2$ state. U phase Hall sensor input Logic high is the $U_{IN}1 > U_{IN}2$ state.

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